

Amendments to the Claims:

Claims 1-39 are currently being amended.

Claims 40-45 are being added.

This amendment adds, changes and/or deletes claims in this application. A detailed listing of all claims that are, or were, in the application, irrespective of whether the claim(s) remain under examination in the application, are presented. The text of all claims presently under examination is presented below in the listing of claims, and all claims are presented with an appropriate defined status identifier.

Detailed and Complete Listing of Claims:

1. (Currently Amended) A robot, comprising: for executing a robot control program module,

~~the robot receiving a new robot control program module from a communication line and writing the new robot control program module in a recording section of the robot.~~

a storage unit for storing a first robot control program module;

a data processor for executing the first robot control program module; and

a data communicator for receiving a second robot control program module;

wherein when the data communicator receives the second robot control program module, the second robot control program module is stored in the storage unit along with the first robot control program module and is executed by the data processor.

2. (Currently Amended) A robot, comprising:

receiver means for receiving a new robot control program module from a communication line;

register means for adding the new robot control program module received by the receiver means to the robot;

selector means for selecting a robot control program module to be executed from a robot control program module originally included in the robot and the new robot control program module added to the robot; and

control program executor means for executing the robot control program module selected by the selector means.

3. (Currently Amended) The robot, in accordance with claim 2, further comprising an initialization program executor means for executing an initialization program included in the

new robot control program module registered by the register means, at the registration of the new robot control program module,

the initialization program determining an execution point of time of the new robot control program module.

4. (Currently Amended) The robot in accordance with claim 2, further comprising an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the new robot control program module; and

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the initialization program determining an execution point of time of the new robot control program module; and

the voice recognition words being used to call the new robot control program module registered by the register means.

5. (Currently Amended) The robot in accordance with claim 2, further comprising

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the voice recognition words being used to call the new robot control program module registered by the register means.

6. (Currently Amended) The robot in accordance with claim 2, further comprising a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof.

7. (Currently Amended) The robot in accordance with claim 2, further comprising a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof; the received program executor means erases, after having executed the new robot control program module, the new robot control program module.

8. (Currently Amended) A robot, comprising:

A
a receiver means for receiving a new robot control program module from a communication line;

a register means for adding the new robot control program module received by the receiver means to the robot;

a selector means for selecting a robot control program module to be executed from a robot control program module originally included in the robot and the new robot control program module added to the robot; and

a control program executor means for executing the robot control program module selected by the selector means; and the receiver means uses an internet as the communication line and receives the new robot control program module by the internet electronic mail.

9. (Currently Amended) The robot, in accordance with claim 8, further comprising an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the control program module,

the initialization program determining an execution point of time of the new robot control program module.

10. (Currently Amended) The robot in accordance with claim 8, further comprising an initialization program executor means for executing an initialization program included in the

new robot control program module registered by the register means, at the registration of the new robot control program module; and

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the initialization program determining an execution point of time of the new robot control program module; and

the voice recognition words being used to call the new robot control program module registered by the register means.

11. (Currently Amended) The robot in accordance with claim 8, further comprising

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the voice recognition words being used to call the new robot control program module registered by the register means.

12. (Currently Amended) The robot in accordance with claim 8, further comprising a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof.

13. (Currently Amended) The robot in accordance with claim 8, further comprising a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof; the received program executor means erases, after having executed the new robot control program module, the new robot control program module.

14. (Currently Amended) A robot control system, comprising: for executing a robot control program module,

~~the robot control system receiving a new robot control program module from a communication line and writing the new robot control program module in a recording section of the robot.~~

a storage unit for storing a first robot control program module;

a data processor for executing the first robot control program module; and

a data communicator for receiving a second robot control program module;

wherein when the data communicator receives the second robot control program module, the second robot control program module is stored in the storage unit along with the first robot control program module and is executed by the data processor.

15. (Currently Amended) A robot control system, comprising:

receiver means for receiving a new robot control program module from a communication line;

register means for adding the new robot control program module received by the receiver means to the robot control system;

selector means for selecting a robot control program module to be executed from a robot control program module originally included in the robot control system and the new robot control program module added to the robot control system; and


control program executor means for executing the robot control program module selected by the selector means.

16. (Currently Amended) The robot control system, in accordance with claim 15, further comprising

an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the new robot control program module,

the initialization program determining an execution point of time of the new robot control program module.

17. (Currently Amended) The robot control system in accordance with claim 15, further comprising

 an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the new robot control program module; and

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the initialization program determining an execution point of time of the new robot control program module; and

the voice recognition words being used to call the new robot control program module registered by the register means.

18. (Currently Amended) The robot control system in accordance with claim 15, further comprising

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the voice recognition words being used to call the new robot control program module registered by the register means.

19. (Currently Amended) The robot control system in accordance with claim 15, further comprising a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof.

20. (Currently Amended) The robot control system in accordance with claim 15, further comprising a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof;

the received program executor means erases, after having executed the new robot control program module, the new robot control program module.

21. (Currently Amended) A robot control system, comprising:

a receiver means for receiving a new robot control program module from a communication line;

a register means for adding the new robot control program module received by the receiver means to the robot control system;

a selector means for selecting a robot control program module to be executed from a robot control program module originally included in the robot control system and the new robot control program module added to the robot control system; and

a control program executor means for executing the robot control program module selected by the selector means; and

the receiver means uses an internet as the communication line and receives the new robot control program module by the internet ~~electronic mail~~.

22. (Currently Amended) The robot control system, in accordance with claim 21, further comprising

an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the new robot control program module; and

the initialization program determining an execution point of time of the new robot control program module.

23. (Currently Amended) The robot control system in accordance with claim 21, further comprising

an initialization program executor means for executing an initialization program included in the new robot control program module registered by the register means, at the registration of the new robot control program module; and

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the initialization program determining an execution point of time of the new robot control program module; and

the voice recognition words being used to call the new robot control program module registered by the register means.

24. (Currently Amended) The robot control system in accordance with claim 21, further comprising

a voice recognition word adder means for adding voice recognition words to a voice recognizer dictionary,

the voice recognition words being used to call the new robot control program module registered by the register means.

25. (Currently Amended) The robot control system in accordance with claim 21, further comprising

a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof.

26. (Currently Amended) The robot control system in accordance with claim 21, further comprising

A
a received program executor means for executing the new robot control program module received by the receiver means, at the reception thereof;

the received program executor means erases, after having executed the new robot control program module, the new robot control program module.

27. (Currently Amended) A program storage medium storing a program which, when executed on a computer controlling a robot, causes said computer to perform the steps of: for making a computer execute a robot control program module for a robot,

receiving a first robot control program module from a communication line and writing the first robot control program module in a recording section of the robot; and

the program receiving a new second robot control program module from a the communication line and writing the new second robot control program module in a the recording section of the robot along with the first robot control program module.

28. (Currently Amended) A ~~program for use with a robot, comprising~~ program storage medium storing a program which, when executed on a computer controlling a robot, causes said computer to perform the steps of:

receiving a new robot control program module from a communication line;

~~additionally~~ registering the received new robot control program module in the robot ~~received by the receiver means to the robot control system;~~

selecting a robot control program module to be executed from a robot control program module originally included in the robot and the new robot control program module received ~~by added to the robot;~~ and

executing the selected robot control program module ~~selected by the selector means.~~

29. (Currently Amended) A program storage medium storing a program in accordance with claim 28, wherein the receiving step uses an internet as the communication line and receives the new robot control program module by electronic mail.

30. (Currently Amended) The program storage medium storing a program in accordance with claim 28, further comprising the steps of making a the computer execute an initialization program execution step,

the initialization program execution step executing an initialization program included in the new robot control program module ~~registered by the register means, at the registration of~~ when the new robot control program module is registered in the robot.

31. (Currently Amended) The program storage medium storing a program in accordance with claim 28, further comprising the steps of making a the computer execute an initialization program execution step and a voice recognition word adder step,

the initialization program execution step executing an initialization program included in the new robot control program module ~~registered by the register means, at the registration of~~ when the new robot control program module is registered in the robot;

the voice recognition word adder step ~~means for~~ adding voice recognition words to a voice recognizer dictionary; ~~and~~

the voice recognition words being used to call the new robot control program module registered by the registering step ~~register means~~.

32. (Currently Amended) The program storage medium storing a program in accordance with claim 28, further comprising the steps of making a the computer execute a voice recognition word adder step,

the voice recognition word adder step adding voice recognition words to a voice recognizer dictionary,

the voice recognition words being used to call the new robot control program module registered by the registering step.

33. (Currently Amended) The program storage medium storing a program in accordance with claim 28, further comprising the steps of making a the computer execute a received program executing step of executing the new robot control program module ~~received by the receiver means~~, at the reception thereof in the receiving step.

34. (Currently Amended) The program storage medium storing a program in accordance with claim 28, further comprising the steps of

executing the new robot control program module ~~received by the receiver means~~, at the reception thereof in the receiving step; and

~~the received program executing step includes~~ erasing the new robot control program module, after having executed the new robot control program module.

35. (Currently Amended) A ~~program for use with a robot, comprising~~ program storage medium storing a program which, when executed on a computer controlling a robot, causes said computer to perform the steps of:

receiving a new robot control program module from a communication line;

~~additionally~~ registering the received new robot control program module in the robot
~~received by the receiver means to the robot control system;~~

selecting a robot control program module to be executed from a robot control program
module originally included in the robot and the new robot control program module received
by ~~added to~~ the robot; and

executing the selected robot control program module ~~selected by the selector means;~~
and

~~the receiver means uses~~ wherein the receiving step includes using an internet as the
communication line ~~and receives the control program module by electronic mail.~~

36. (Currently Amended) The program storage medium storing a program in accordance
with claim 35, further comprising the steps of making a the computer execute an initialization
program execution step,

the initialization program execution step executing an initialization program included
in the new robot control program module ~~registered by the register means,~~ at the registration
of when the new robot control program module is registered in the robot

the ~~initiation~~ initialization program determining an execution point of time of the new
robot control program module.

37. (Currently Amended) The program storage medium storing a program in accordance
with claim 35, further comprising the steps of making a the computer execute an initialization
program execution step and a voice recognition word adder step,

the initialization program execution step executing an initialization program included
in the new robot control program module ~~registered by the register means,~~ at the registration
of when the new robot control program module is registered in the robot;

the voice recognition word adder step ~~means for~~ adding voice recognition words to a voice recognizer dictionary; and

the voice recognition words being used to call the new robot control program module registered by the registering step ~~register means~~.

38. (Currently Amended) The program storage medium storing a program in accordance with claim 35, further comprising the steps of making a the computer execute a received program executing step of executing the new robot control program module ~~received by the receiver means~~, at the reception thereof in said receiving step.

39. (Currently Amended) The program storage medium storing a program in accordance with claim 35, further comprising the steps of making a the computer execute a received program executing step of executing the new robot control program module ~~received by the receiver means~~, at the reception thereof in said receiving step wherein;

the received program executing step includes erasing, after having executed the new robot control program module.

40. (New) A robot, comprising:

a receiver for receiving a new robot control program module from a communication line;

a register for adding the new robot control program module received by the receiver to the robot;

a selector for selecting a robot control program module to be executed from a robot control program module originally included in the robot and the new robot control program module added to the robot; and

a control program executor for executing the robot control program module selected by the selector.

41. (New) The robot, in accordance with claim 40, further comprising an initialization program executor for executing an initialization program included in the new robot control program module registered by the register, at the registration of the new robot control program module,

the initialization program determining an execution point of time of the new robot control program module.

42. (New) The robot in accordance with claim 40, further comprising an initialization program executor for executing an initialization program included in the new robot control program module registered by the register, at the registration of the new robot control program module; and

a voice recognition word adder for adding voice recognition words to a voice recognizer dictionary,

the initialization program determining an execution point of time of the new robot control program module; and

the voice recognition words being used to call the new robot control program module registered by the register.

43. (New) The robot in accordance with claim 40, further comprising

a voice recognition word adder for adding voice recognition words to a voice recognizer dictionary,

the voice recognition words being used to call the new robot control program module registered by the register.

44. (New) The robot in accordance with claim 40, further comprising a received program executor for executing the new robot control program module received by the receiver, at the reception thereof.

45. (New) The robot in accordance with claim 40, further comprising a received program executor for executing the new robot control program module received by the receiver, at the reception thereof; the received program executor erases, after having executed the new robot control program module, the new robot control program module.
